

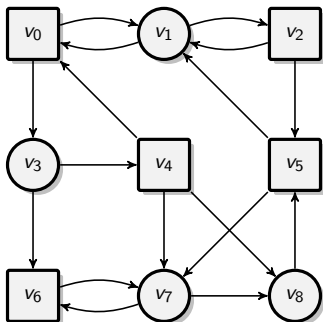
Reactive Synthesis

Lecture 2

Swen Jacobs and Martin Zimmermann
(Saarland University)

Recap

A game $\mathcal{G} = (\mathcal{A}, \text{Win})$ consists of an arena $\mathcal{A} = (V, V_0, V_1, E)$ and a winning condition $\text{Win} \subseteq V^\omega$.



$$\text{Win} = \{\rho_0\rho_1\rho_2\cdots \in V^\omega \mid \exists v \in V \text{ such that } \rho_n \neq v \text{ for all } n\}$$

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- A play $\rho = \rho_0\rho_1\rho_2\cdots$ is an infinite path through \mathcal{A} .
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- σ is positional if $\sigma(wv) = \sigma(v)$ for all $w \in V^*$ and all $v \in V_i$.
- ρ is consistent with σ if $\rho_{n+1} = \sigma(\rho_0 \cdots \rho_n)$ for every $n \in \mathbb{N}$ with $\rho_n \in V_i$.

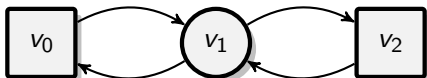
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- σ is a winning strategy for \mathcal{G} from $v \in V$ if every play that is consistent with σ and starts in v is winning for Player i .
- the winning region of Player i in \mathcal{G} :
 $W_i(\mathcal{G}) = \{v \in V \mid \text{Player } i \text{ has winning strategy for } \mathcal{G} \text{ from } v\}$

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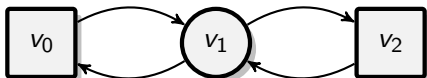
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 $W_i(\mathcal{G}) = \{v \in V \mid \text{Player } i \text{ has winning strategy for } \mathcal{G} \text{ from } v\}$
- Solving \mathcal{G} : determine winning regions and winning strategies.

Another Example



Win = $\{\rho \mid \rho \text{ visits } v_0 \text{ and } v_2 \text{ infinitely often}\}$

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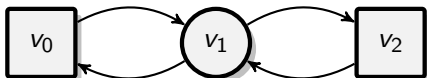


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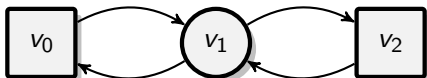
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- But both positional strategies for Player 0 are not winning from any vertex.
- Thus, positional strategies are not always sufficient.

Recap

Let $\mathcal{G} = (\mathcal{A}, \text{Win})$ be a game with vertex set V .

- \mathcal{G} is a safety game if there is a set $S \subseteq V$ such that

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Remark

Safety and reachability games and are dual:

	Player 0	Player 1
Safety	Avoid $V \setminus S$	Reach $V \setminus S$
Reachability	Reach R	Avoid R

Plan for Today

- Basic Games
- Algorithms & Data Structures
- Advanced Games
- Temporal Logic Synthesis

Plan for Today

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 - Solving reachability and safety games
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Duality

Definition

Let $\mathcal{A} = (V, V_0, V_1, E)$ be an arena and let $\mathcal{G} = (\mathcal{A}, \text{Win})$.

1. The *dual arena* $\overline{\mathcal{A}}$ of \mathcal{A} is defined as $\overline{\mathcal{A}} = (V, V_1, V_0, E)$.
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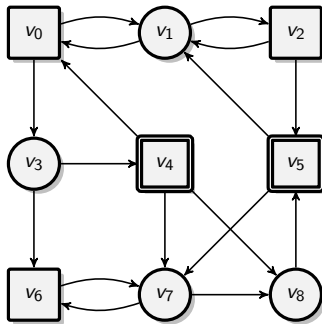
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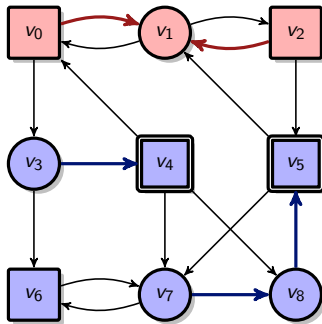
Proof.

On the blackboard. □

Solving Reachability Games



Solving Reachability Games



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- The *controlled predecessor* $\text{CPre}_0(R)$ of R is defined as

$$\text{CPre}_0(R) = \{v \in V_0 \mid v' \in R \text{ for some successor } v' \text{ of } v\} \cup \\ \{v \in V_1 \mid v' \in R \text{ for all successors } v' \text{ of } v\}.$$

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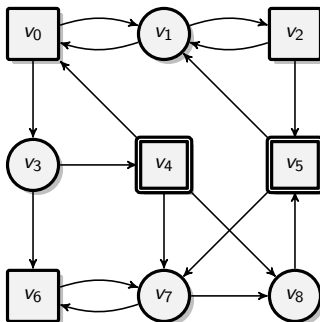
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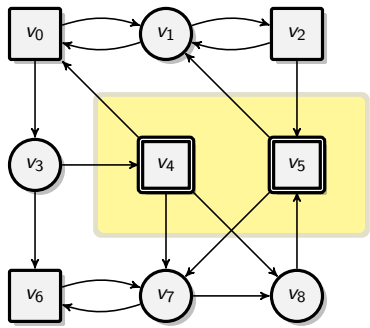
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 - $\text{Attr}_0(R) = \bigcup_{n \in \mathbb{N}} \text{Attr}_0^n(R)$.

Example

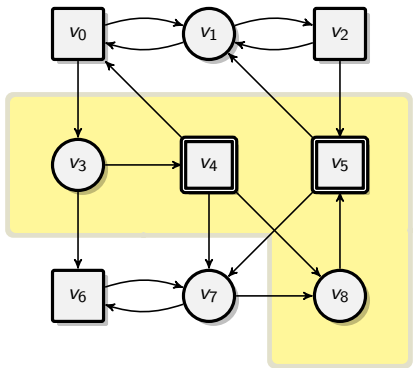


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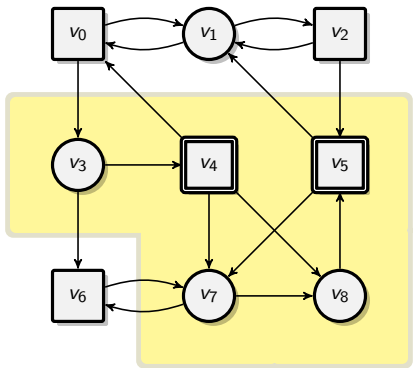
$$\text{Attr}_0^0(\{v_4, v_5\}) = \{v_4, v_5\}$$

Example



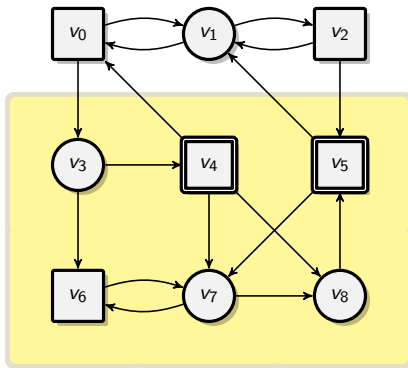
$$\text{Attr}_0^1(\{v_4, v_5\}) = \{v_4, v_5\} \cup \{v_3, v_8\}$$

Example



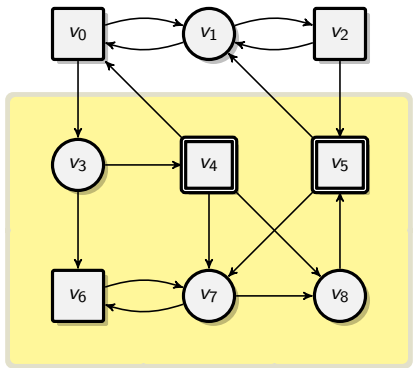
$$\text{Attr}_0^2(\{v_4, v_5\}) = \{v_3, v_4, v_5, v_8\} \cup \{v_3, v_7, v_8\}$$

Example



$$\text{Attr}_0^3(\{v_4, v_5\}) = \{v_3, v_4, v_5, v_7, v_8\} \cup \{v_3, v_6, v_7, v_8\}$$

Example



$$\text{Attr}_0^4(\{v_4, v_5\}) = \{v_3, v_4, v_5, v_6, v_7, v_8\}$$

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Lemma

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On the blackboard. □

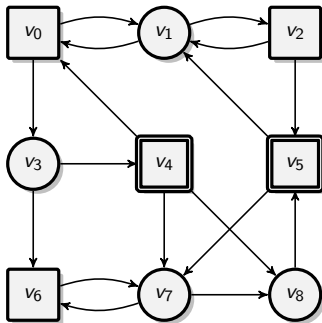
Computing Attractors Efficiently

- 1: **for all** $v \in V$ **do** ▷ Initialization
- 2: **if** $v \in R$ **then** $c(v) \leftarrow 0$
- 3: **else if** $v \in V_0 \setminus R$ **then** $c(v) \leftarrow 1$
- 4: **else if** $v \in V_1 \setminus R$ **then** $c(v) \leftarrow |\{v' \mid (v, v') \in E\}|$
- 5: **end if**
- 6: **end for**

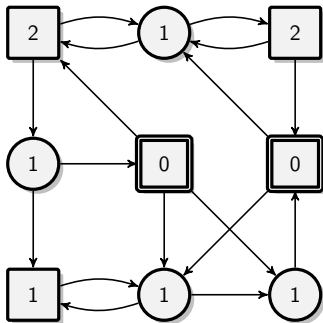
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5:   end if
6: end for
7:  $A = R$ 
8: while  $A \neq \emptyset$  do ▷ Main Loop
9:   remove some  $v$  from  $A$ 
10:  for all  $(v', v) \in E$  with  $c(v') > 0$  do
11:     $c(v') \leftarrow c(v') - 1$ 
12:    if  $c(v') = 0$  then  $A \leftarrow A \cup \{v'\}$ 
13:    end if
14:  end for
15: end while
16: return  $\{v \mid c(v) = 0\}$ 
```

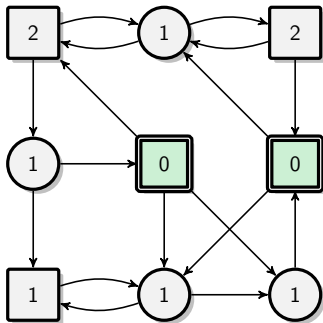
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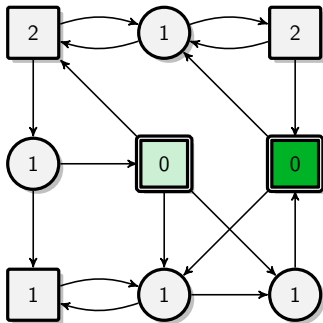


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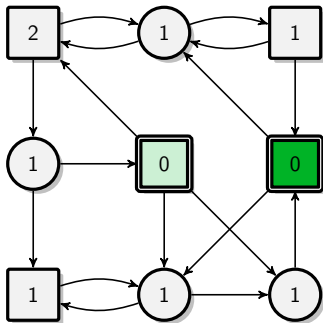
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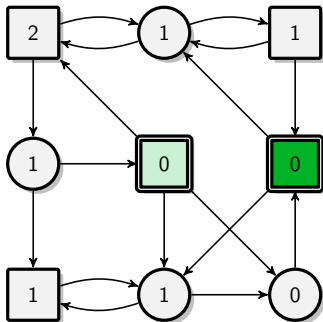
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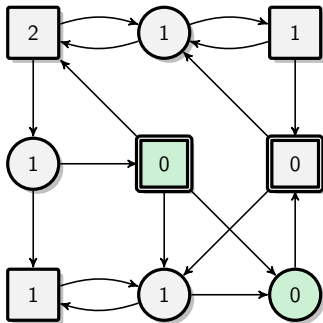
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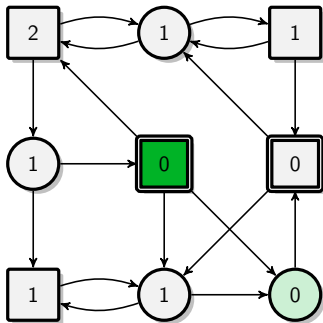
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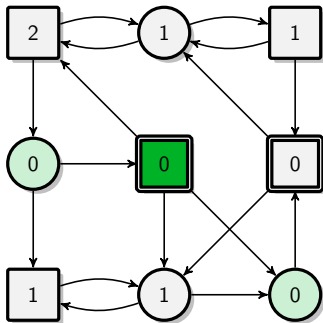
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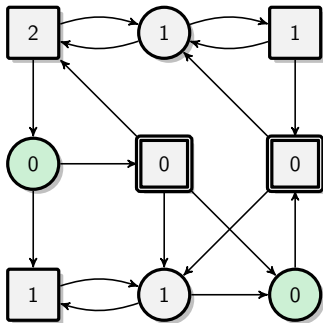
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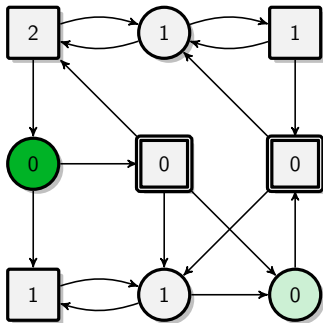
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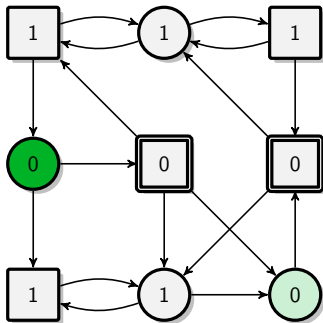
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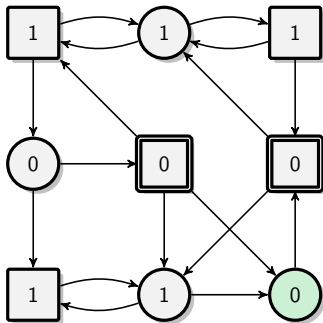
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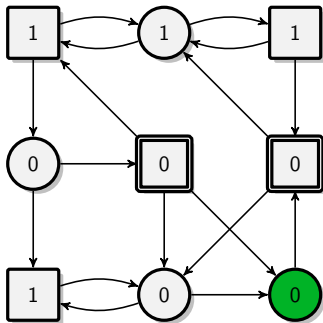
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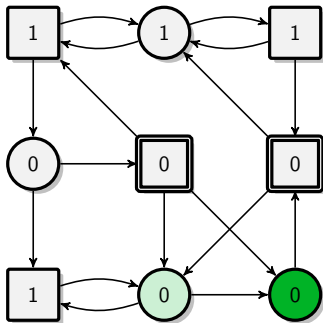
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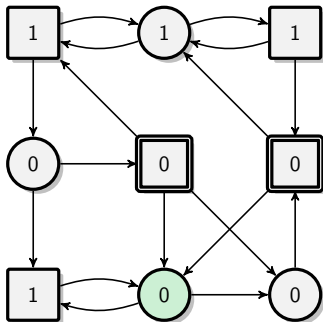
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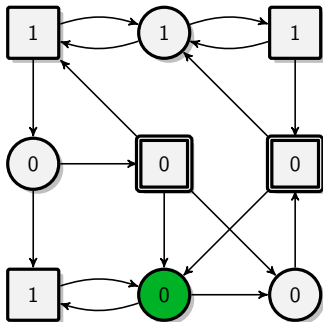
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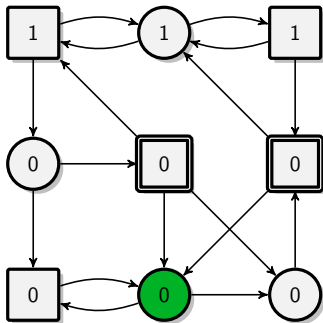
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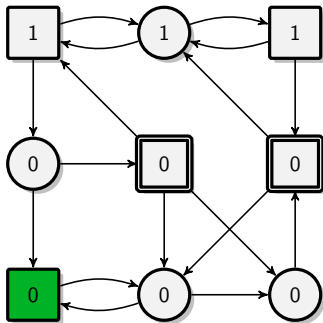
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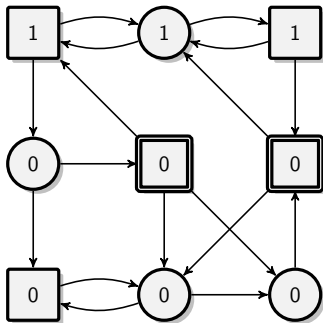
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Running time

- Recall: $|V| \leq |E|$.
- Initialization takes time $\mathcal{O}(|V|)$.
- Every v is added to A at most once.

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- Recall: $|V| \leq |E|$.
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- Every v is added to A at most once.
- Thus: the main loop terminates after at most $|V|$ iterations.
- Also: the for-loop in line 10 considers each edge at most once.

Analysis

Correctness

Sketch: By constructing winning strategies, show that..

- .. the output is a subset of $W_0(\mathcal{G})$.
- .. the complement of the output is a subset of $W_1(\mathcal{G})$.

Then, the output is equal to $W_0(\mathcal{G}) = \text{Attr}_0(R)$.

Running time

- Recall: $|V| \leq |E|$.
- Initialization takes time $\mathcal{O}(|V|)$.
- Every v is added to A at most once.
- Thus: the main loop terminates after at most $|V|$ iterations.
- Also: the for-loop in line 10 considers each edge at most once.

Hence, the overall running time is bounded by $|E|$.

Theorem

Reachability and safety games are determined with positional strategies and can be solved in linear time (in the number of edges).

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Remark

The algorithm can easily be modified to compute winning strategies for both players, without increasing the running time.

- For Player 0, pick successor that caused decrease of $c(v)$.
- For Player 1, pick successor v' with $c(v') > 0$.

Announcements

Exam dates

- Exam: January 31st, 2018
- Re-exam: March 20th, 2018