

# Introduction to Software Verification

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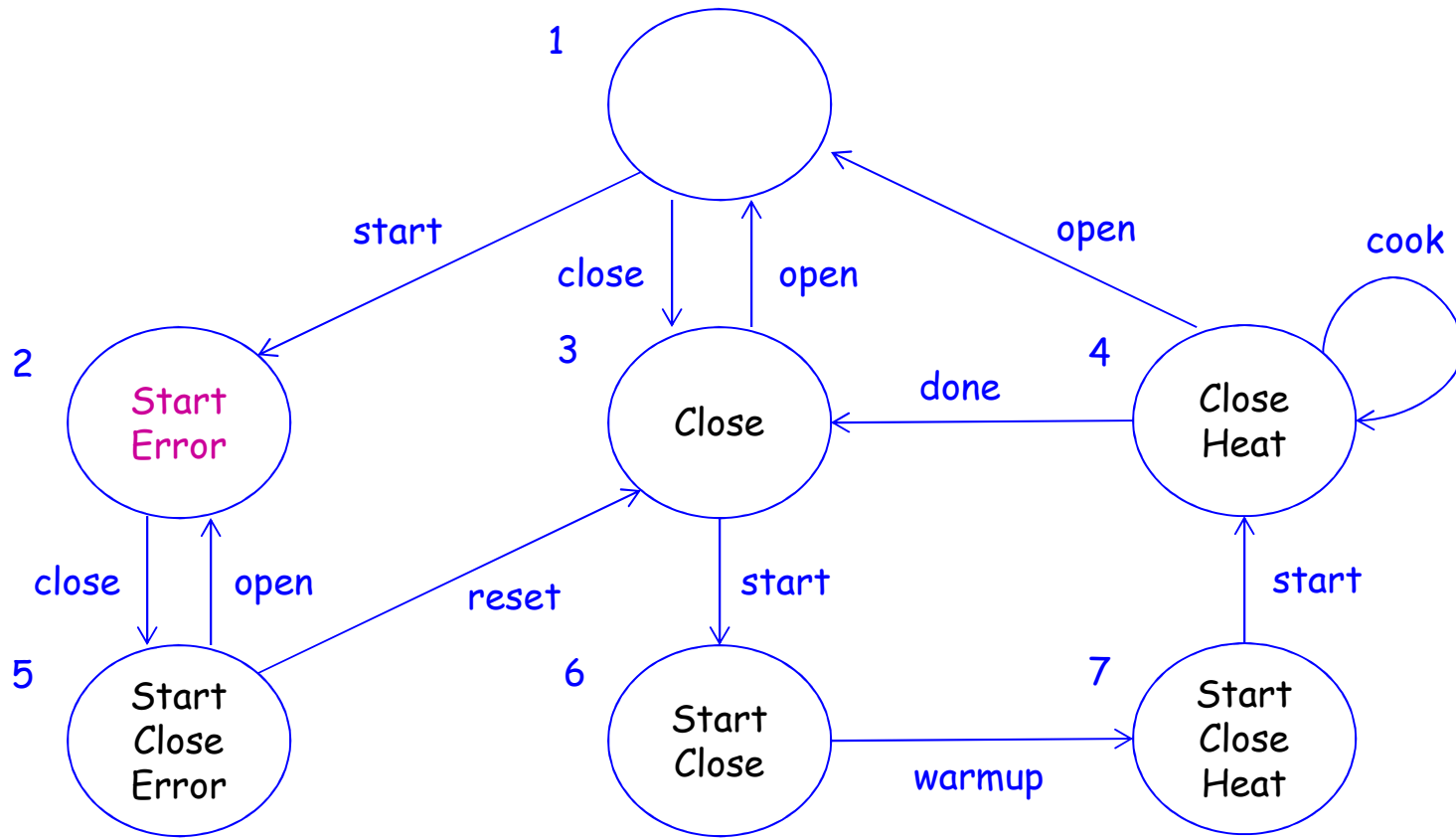
Lectures Material  
winter 2017-18

# Lecture 7

## Model Checking Complexity

- Each subformula requires  $O(|M|)$
- Number of subformulas:  $O(|f|)$
- Total:  $O(|M| \times |f|)$

# Microwave Example



# Property

- $AG (\text{Start} \rightarrow AF \text{Heat})$
- $\neg EF (\text{Start} \wedge EG \neg \text{Heat})$
- $\neg E (\text{true} \cup (\text{Start} \wedge EG \neg \text{Heat}))$

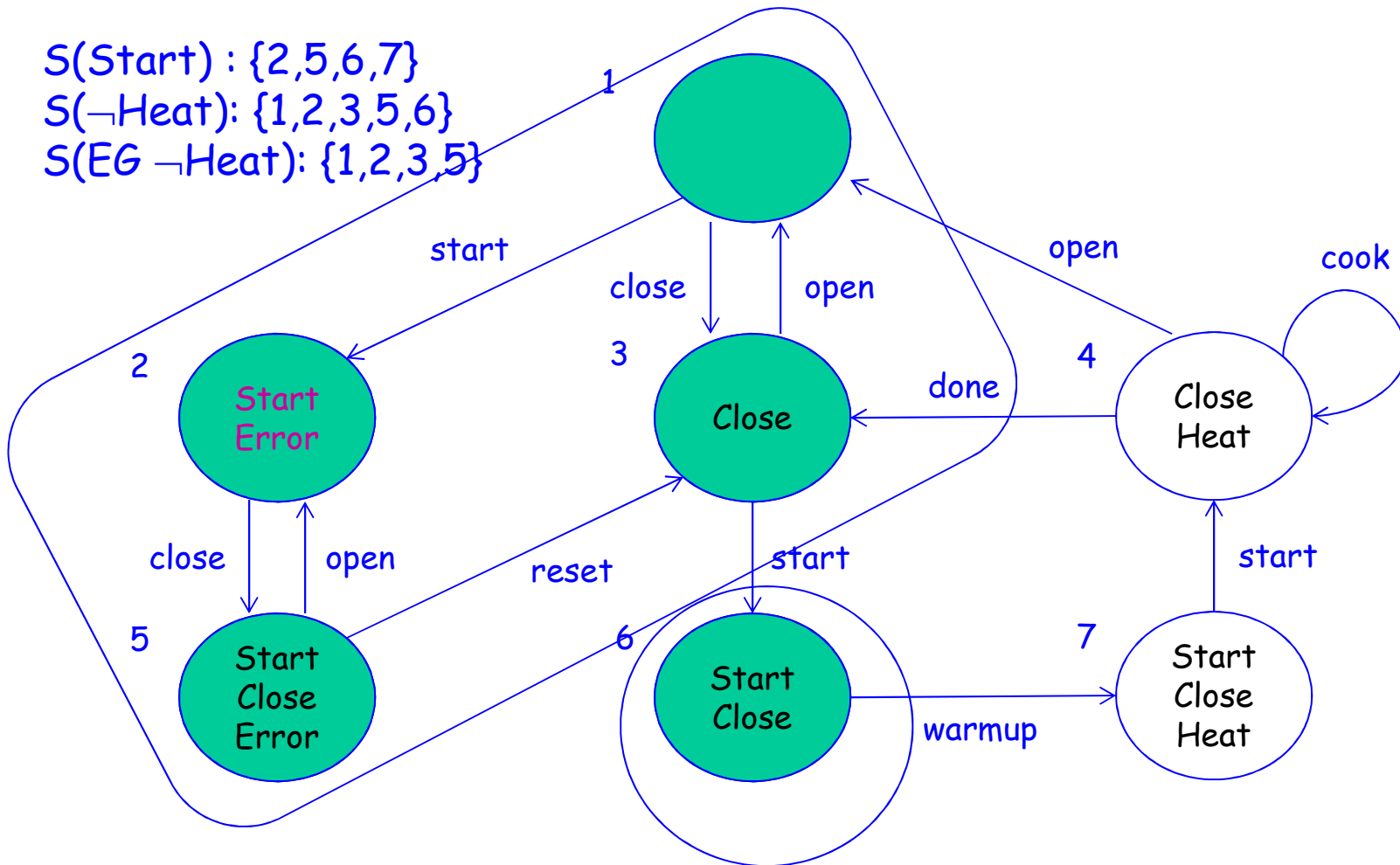
Instead of writing the formulas in  $\text{label}(s)$  for each  $s$ ,  
use  $S(f)$  to denote the set of states  $s$ .t.  $f \in \text{label}(s)$

$\neg E$  (true U (Start  $\wedge$  EG  $\neg$ Heat))

$S(\text{Start}) : \{2,5,6,7\}$

$S(\neg\text{Heat}) : \{1,2,3,5,6\}$

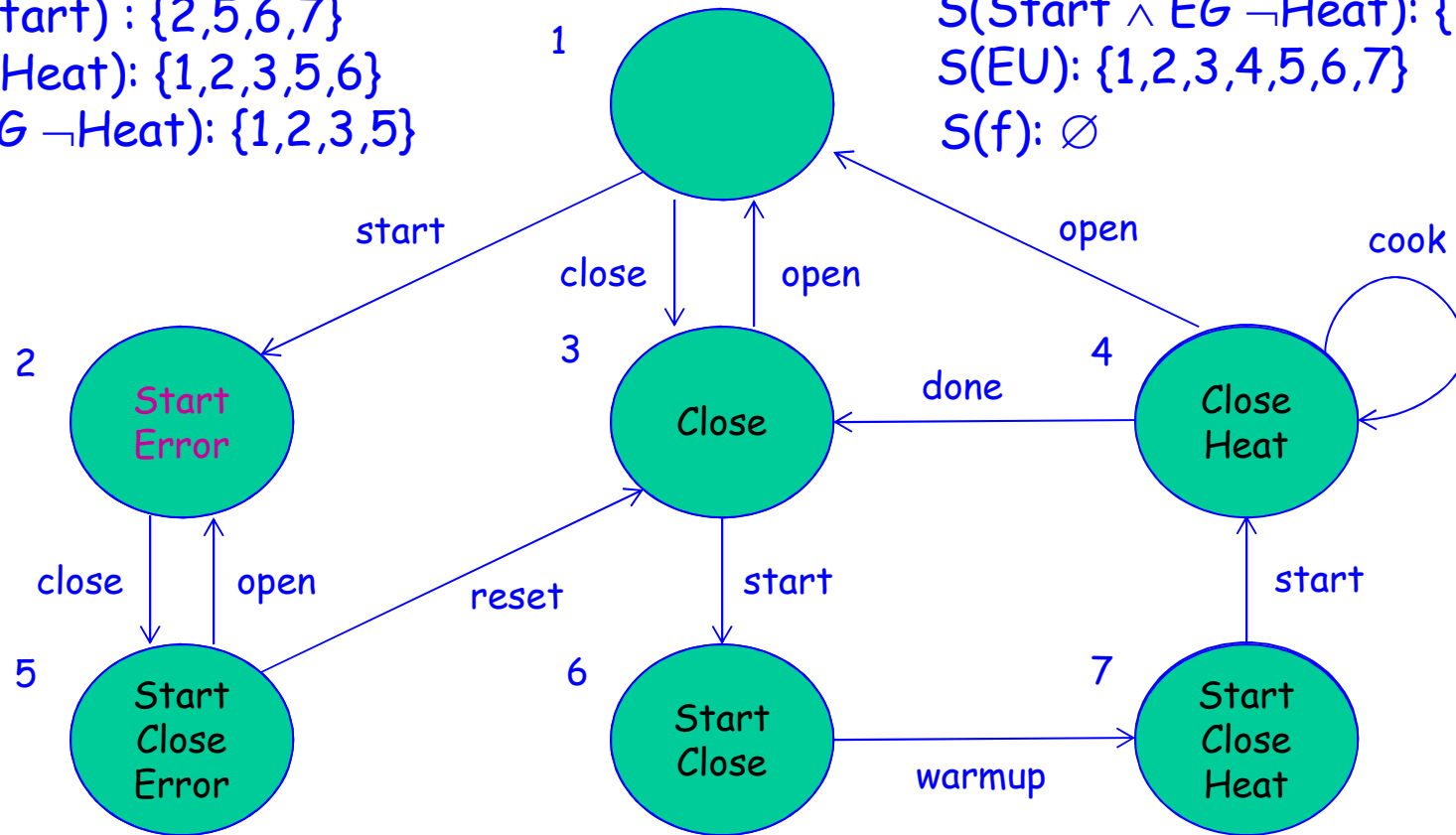
$S(\text{EG } \neg\text{Heat}) : \{1,2,3,5\}$



# $\neg E$ (true U (Start $\wedge$ EG $\neg$ Heat))

$S(\text{Start}) : \{2,5,6,7\}$   
 $S(\neg\text{Heat}) : \{1,2,3,5,6\}$   
 $S(\text{EG } \neg\text{Heat}) : \{1,2,3,5\}$

$S(\text{Start} \wedge \text{EG } \neg\text{Heat}) : \{2, 5\}$   
 $S(\text{EU}) : \{1,2,3,4,5,6,7\}$   
 $S(f) : \emptyset$



# Explicit Model Checking for Fair CTL



# Motivation

## Fair CTL (CTL<sup>F</sup>)

- Same syntax as CTL
- Different semantics

CTL<sup>F</sup> formulas are interpreted over **fair** Kripke structures

# Fair Kripke Structures

Fair Kripke structure  $M = (S, S_0, R, L, F)$

- $S, S_0, R, L$  - as before
- $F \subseteq 2^S$  is a set of fairness constraints
- $F = \{P_1, \dots, P_k\}$  where
- $P_i \subseteq S$   
or
- $P_i$  is a CTL formula

# Fairness

Fair paths:

- $\pi = s_0, s_1, s_2, \dots$
- $\text{inf}(\pi) = \{s \mid s = s_i \text{ for infinitely many } i\}$

$\pi$  is **fair** if for every  $P \in \mathcal{F}$ ,  $\text{inf}(\pi) \cap P \neq \emptyset$

## Example

- $F = \{ \{1,4\}, \{1,6\}, \{3\} \}$
- A path  $\pi$  is fair iff  $\text{inf}(\pi)$  includes one of the sets:
  - $\{1, 3\}$
  - $\{4, 6, 3\}$
  - Or their extensions

## Semantics of Fair CTL

- $M, s \models_F EX \psi \Leftrightarrow$  there exists a **fair** path  $\pi = s_0, s_1, \dots$  from  $s$  such that  $M, s_1 \models_F \psi$
- $M, s \models_F AX \psi \Leftrightarrow$  for every **fair** path  $\pi = s_0, s_1, \dots$  from  $s$ ,  $M, s_1 \models_F \psi$
- Similarly for  $EG, AG, EU, AU, \dots$

# Examples

Fairness constraints for hardware design, expressed as formulas:

- One input that should be 1 infinitely often
- K inputs, **each** should be 1 infinitely often
- K inputs that should be 1 **together** infinitely often

## Model checking Fair CTL

- Needs to consider only fair paths
- $g \in \text{label}(s) \Leftrightarrow M, s \models_{\mathbf{F}} g$



## Reminder: Model Checking $g = EG f_1$ without fairness

Observation:

- $s \models EG f_1$   
iff
- $s$  is the start of a path where all states satisfy  $f_1$   
iff
- $s$  has a finite path to a nontrivial, **Maximal Strongly Connected Component (MSCC)**, where all states satisfy  $f_1$

# Model Checking $g = EG f_1$ with fairness

Observation:

- $s \models_F EG f_1$   
iff
- $s$  is the start of a **fair** path where all states satisfy  $f_1$   
iff
- $s$  has a finite path to a nontrivial Maximal **Fair** Strongly Connected Component (MFSCC), where all states satisfy  $f_1$

$$M, s \models_F EG f_1$$

Strongly connected component  $C$  is fair iff  
for every  $P \in F$ ,  $C \cap P \neq \emptyset$

Reduced structure:

Remove from  $M$  all states s.t.  $f_1 \notin \text{label}(s)$ .

Resulting model:  $M' = (S', R', L', F')$

- $S' = \{ s \mid M, s \models_F f_1 \}$
- $R', L'$  defined as before
- $F' = \{ P_i \cap S' \mid P_i \in F \}$

$$M, s \models_F EG f_1$$

**Theorem:**  $M, s \models_F EG f_1$  iff

1.  $s \in S'$  and
2. There is a path in  $M'$  from  $s$  to some state  $t$  in a nontrivial maximal **fair** strongly connected component of  $M'$

**Proof:** similar to theorem for  $EG$  without fairness

$$M, s \models_F EG f_1$$

procedure **CheckFairEG** ( $f_1$ )

$S' := \{s \mid f_1 \in \text{label}(s)\}$

**MFSCC** :=  $\{C \mid C \text{ is a nontrivial fair MSCC of } M'\}$

$T := \cup_{C \in \text{MFSCC}} \{s \mid s \in C\}$

For all  $s \in T$  do  $\text{label}(s) := \text{label}(s) \cup \{EG f_1\}$

while  $T \neq \emptyset$  do

  choose  $s \in T$ ;  $T := T \setminus \{s\}$ ;

  for all  $t \in S'$  s.t.  $R'(t, s)$  do

    if  $EG f_1 \notin \text{label}(t)$  then

$\text{label}(t) := \text{label}(t) \cup \{EG f_1\}$ ;

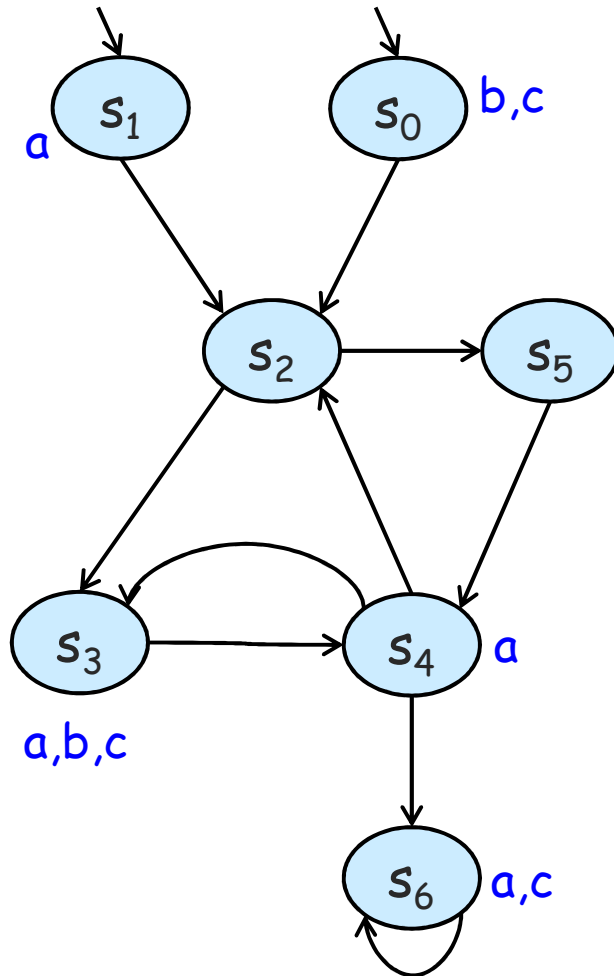
$T := T \cup \{t\}$

  end for all

end while

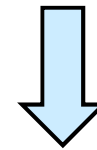
Complexity increases  
to  $O((|S| + |R|) \cdot |F|)$

$M, s \models_F EGa$  with  $F = \{ \{1, 2\}, \{1, 5\} \}$

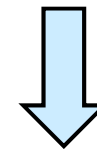


$F' = \{ \{1\} \}$

$MSCC = \{ \{1\}, \{3, 4\}, \{6\} \}$



$FMSCC = \emptyset$



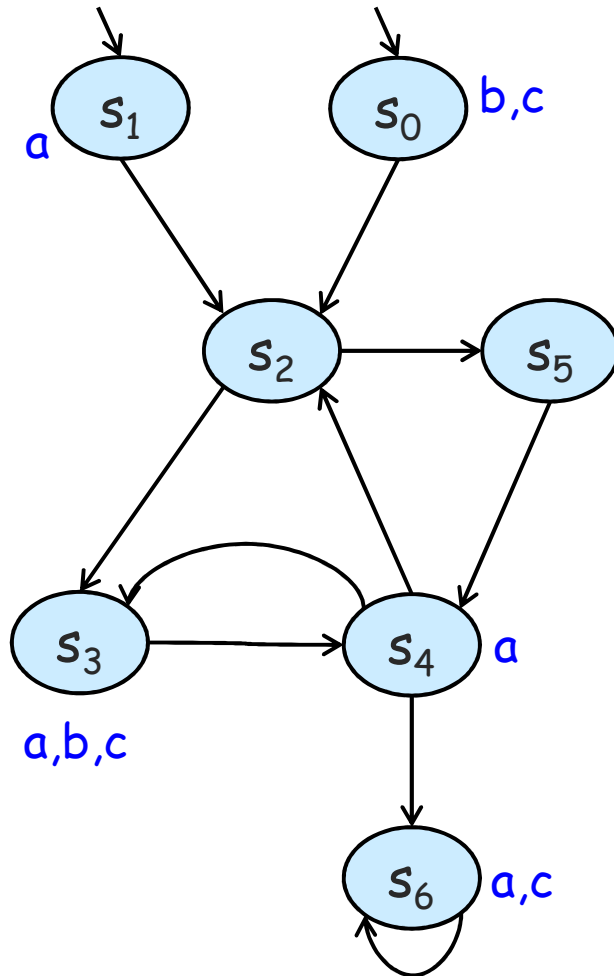
Set of states satisfying  $E_F Ga$  is empty

## Model Checking other Fair CTL Formulas

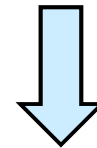
- Add atomic proposition **fair** to all states that satisfy  $M, s \models_F EG \text{ true}$
- $M, s \models_F EX f_1$  iff  $M, s \models EX (f_1 \wedge \text{fair})$
- $M, s \models_F E [f_1 U f_2]$  iff  $M, s \models E [f_1 U (f_2 \wedge \text{fair})]$

Overall complexity:  $O(|f| \cdot (|S| + |R|) \cdot |F|)$

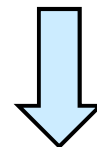
# Computing $S_{\text{fair}}$ with $F = \{ \{1, 2\}, \{1, 5\} \}$



$$\text{MSCC} = \{ \{0\}, \{1\}, \{2,3,4,5\}, \{6\} \}$$



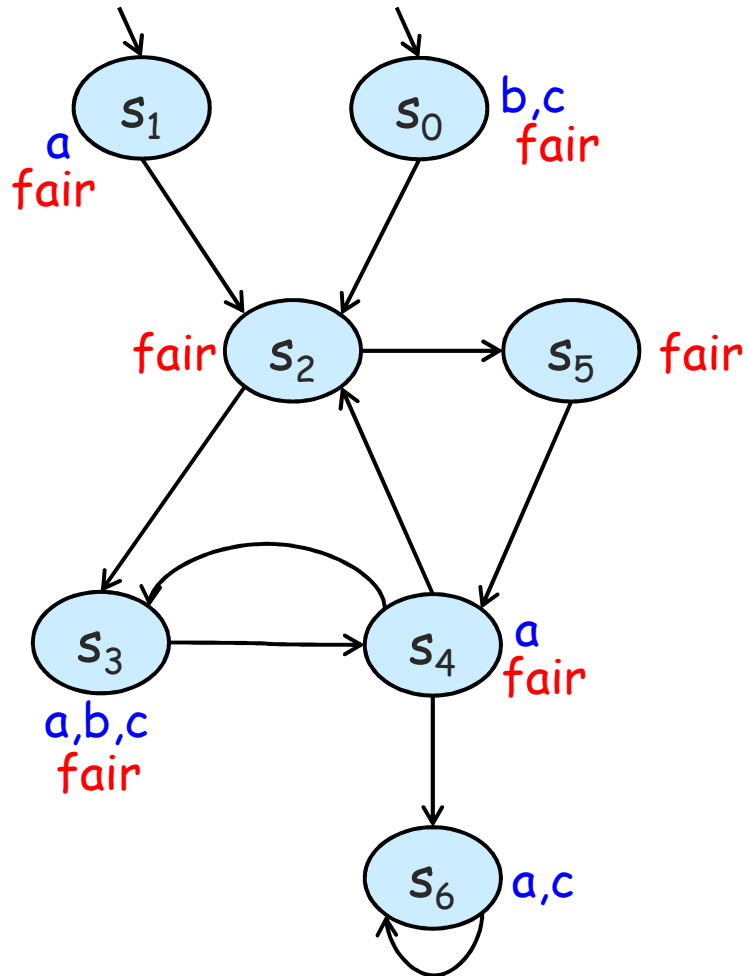
$$\text{FMSCC} = \{ \{2,3,4,5\} \}$$



$$S_{\text{fair}} = \{2,3,4,5\} \cup \{0,1\}$$



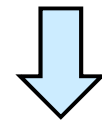
$M, s \models_F E(aUc)$  with  $F = \{ \{1, 2\}, \{1, 5\} \}$



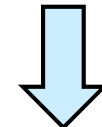
$$S_{\text{fair}} = \{0, 1, 2, 3, 4, 5\}$$

$$E_F(aUc) \equiv E(aU(c \wedge \text{fair})) = \varnothing$$

$$S_a = \{1, 3, 4, 6\} \quad S_c = \{0, 3, 6\}$$



$$S_{\text{fair} \wedge c} = \{0, 3\}$$

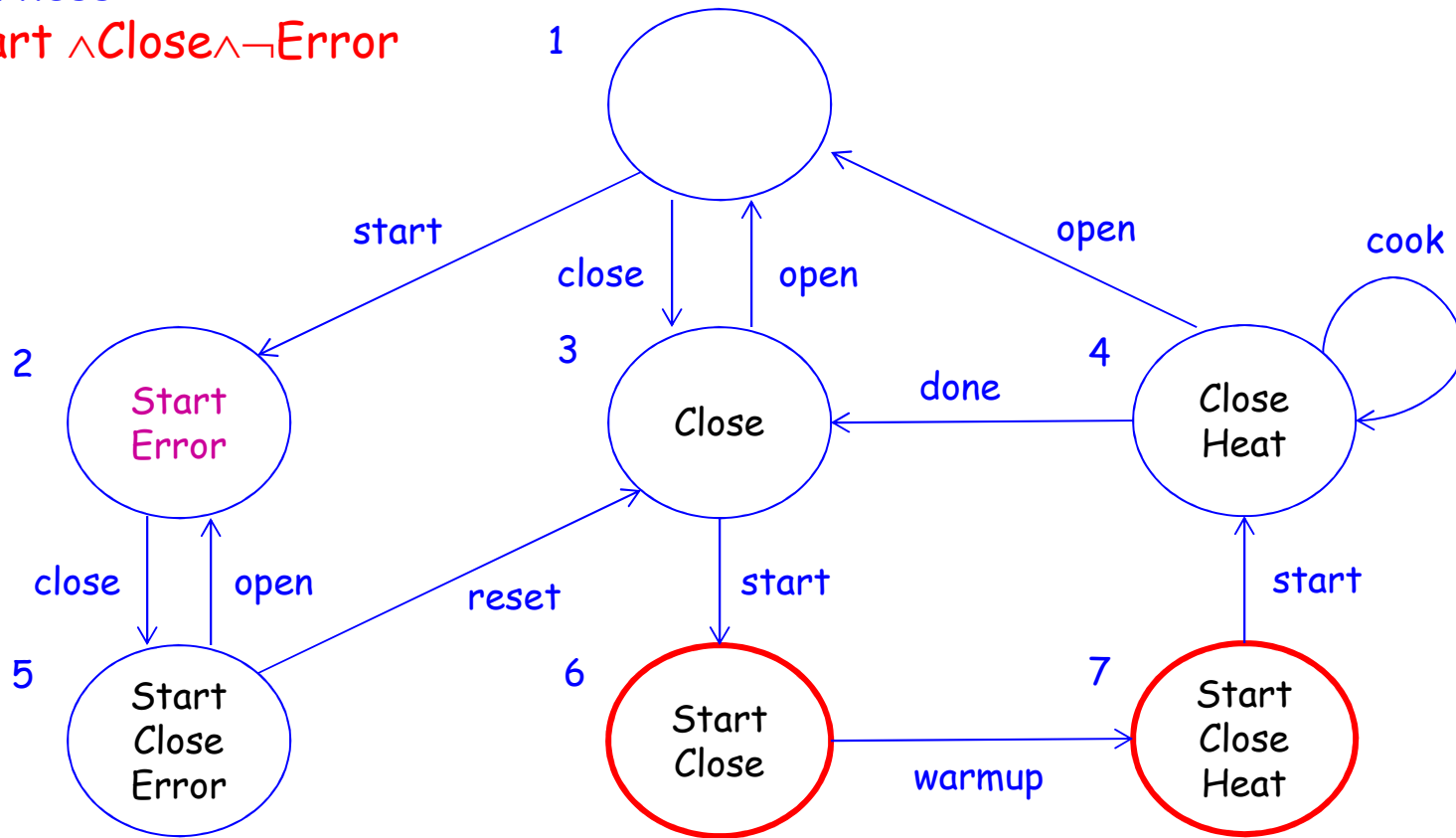


$$S_{\varnothing} = \{0, 3, 4\}$$

# Microwave Example

Fairness:

$Start \wedge Close \wedge \neg Error$

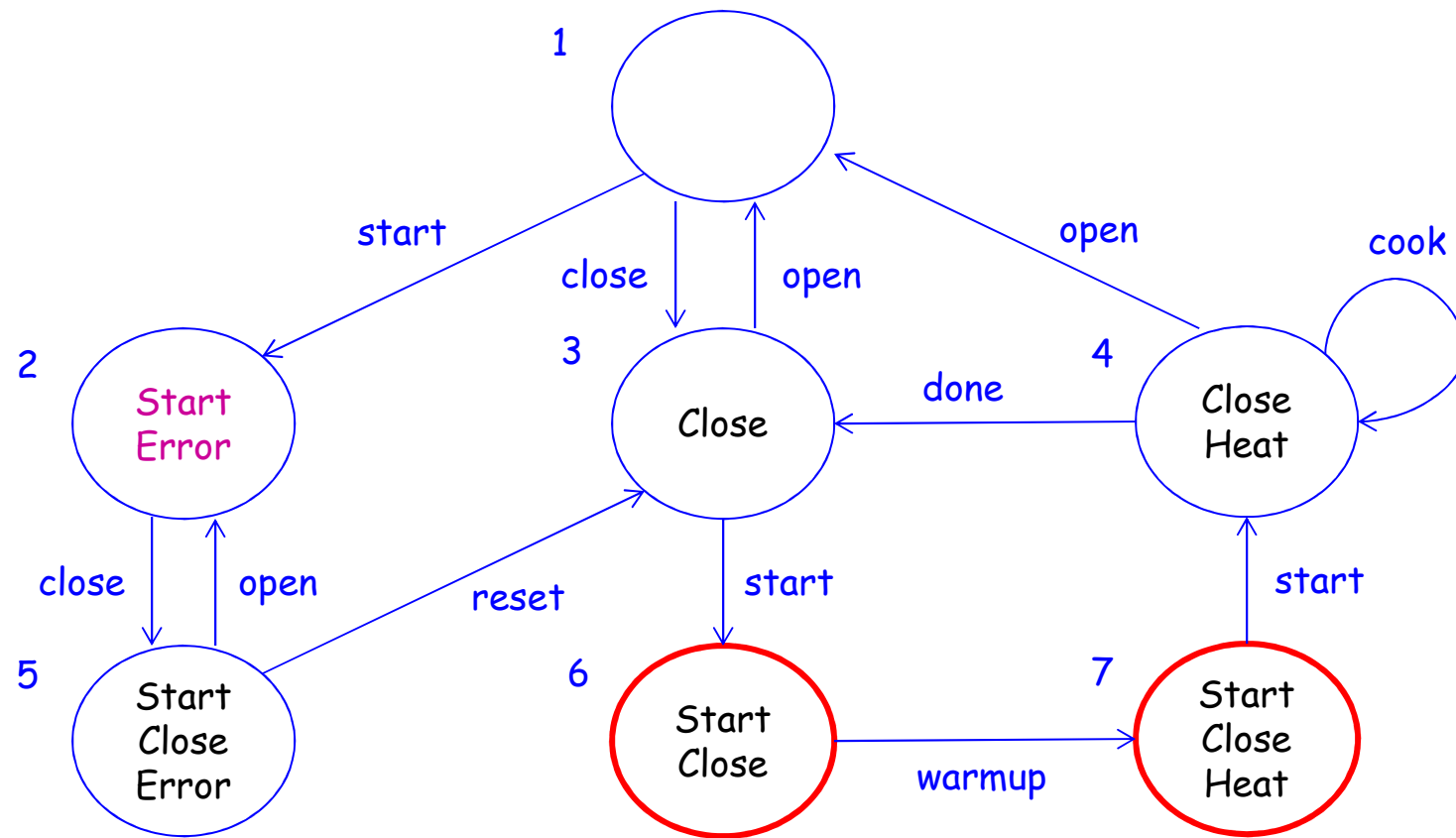


# Property

- $AG (\text{start} \rightarrow AF \text{Heat})$
- $\neg EF (\text{start} \wedge EG \neg \text{Heat})$
- $\neg E (\text{true} U (\text{start} \wedge EG \neg \text{Heat}))$

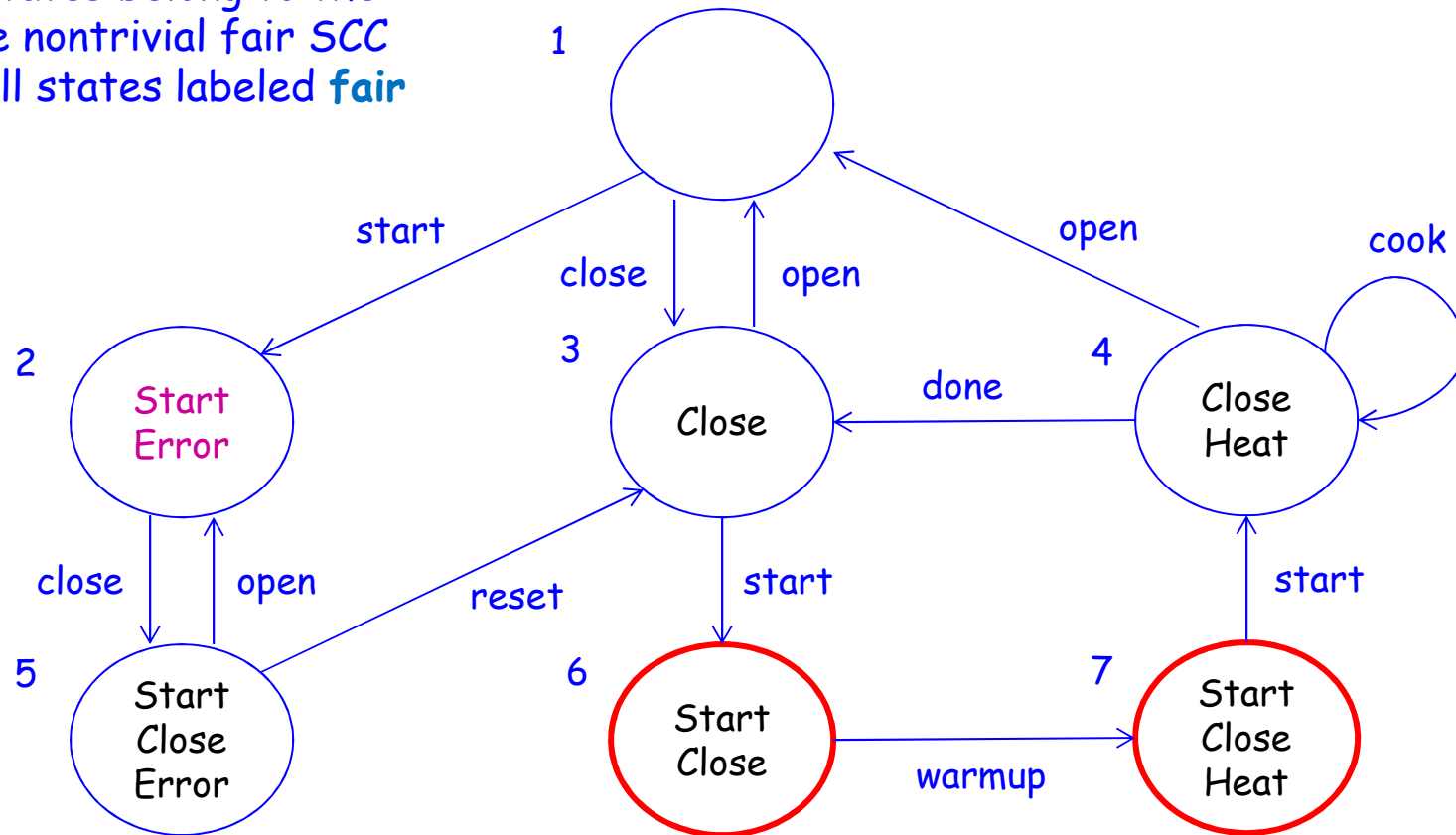
Now we check it with respect to a fair Kripke structure

$\neg E$  (true U (start  $\wedge$  EG  $\neg$ Heat))



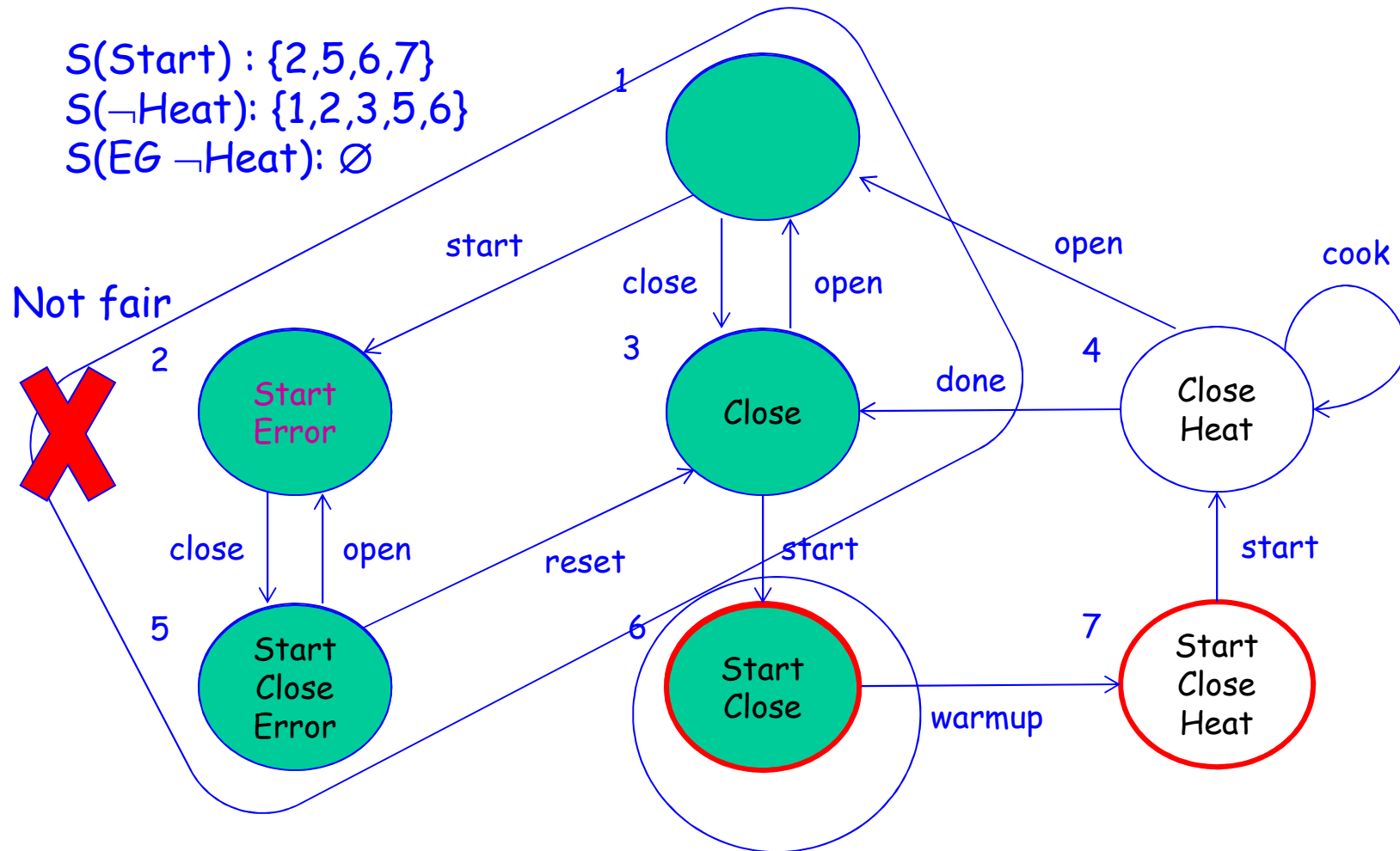
$\neg E (\text{true} \cup (\text{start} \wedge EG \neg \text{Heat}))$

All states belong to the same nontrivial fair SCC  
→ All states labeled **fair**



$\neg E$  (true U (start  $\wedge$  EG  $\neg$ Heat))

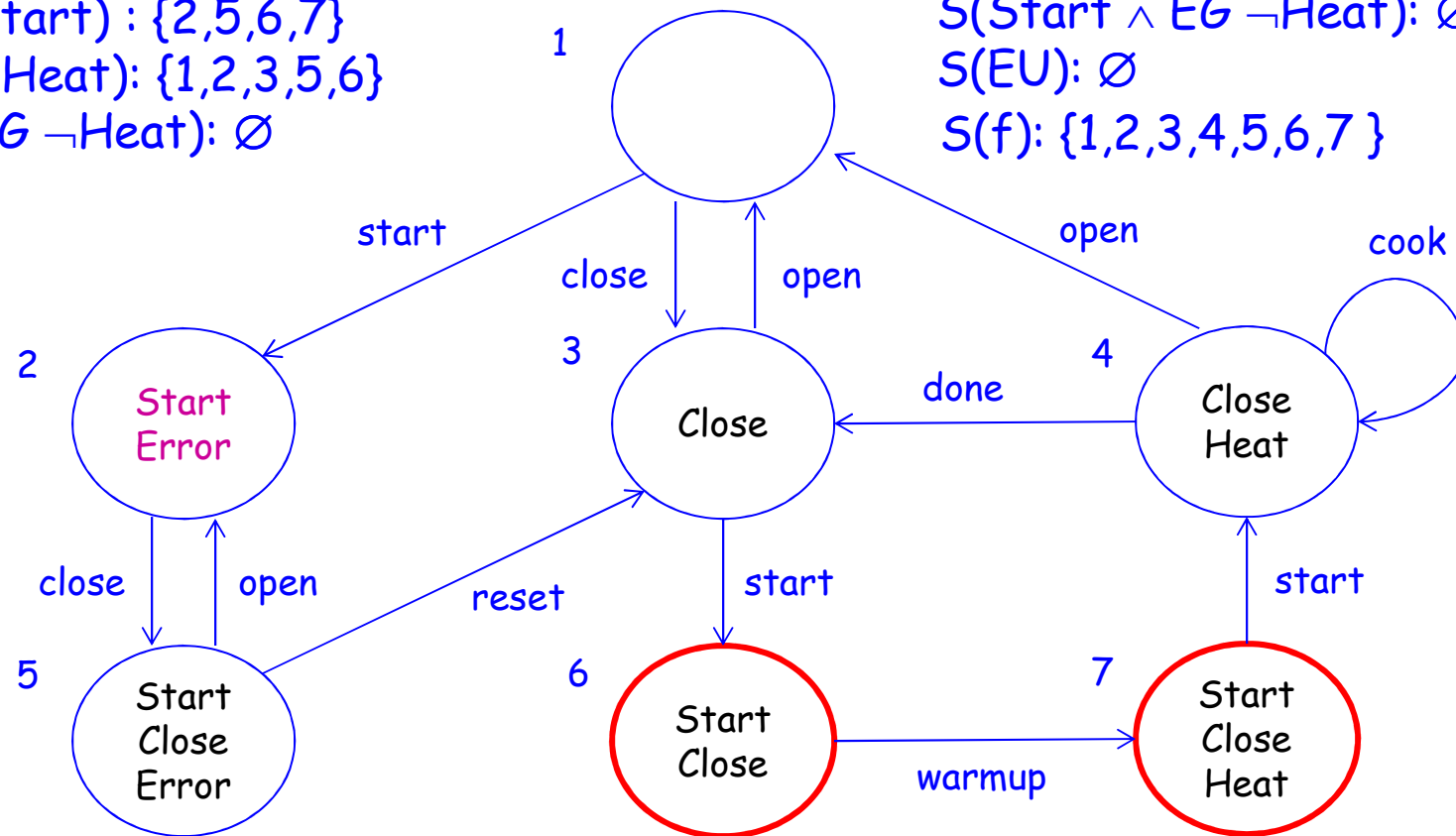
$S(\text{Start}) : \{2,5,6,7\}$   
 $S(\neg\text{Heat}) : \{1,2,3,5,6\}$   
 $S(\text{EG } \neg\text{Heat}) : \emptyset$



# $\neg E$ (true U (start $\wedge$ EG $\neg$ Heat))

$S(\text{Start}) : \{2,5,6,7\}$   
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 $S(\text{EG } \neg\text{Heat}) : \emptyset$

$S(\text{Start} \wedge \text{EG } \neg\text{Heat}) : \emptyset$   
 $S(\text{EU}) : \emptyset$   
 $S(f) : \{1,2,3,4,5,6,7\}$



# Model Checking

- Emerging as an industrial standard tool for verification of **hardware** designs: Intel, IBM, Cadence, Mellanox, ...
- Recently applied successfully also for **software** verification: SLAM (Microsoft), Java PathFinder and SPIN (NASA), BLAST (EPFL), CBMC (Oxford),...



Clarke, Emerson, and Sifakis won the 2007  
Turing award for their contribution to  
Model Checking

# Main Limitation of Model Checking:

## The state explosion problem:

Model checking is efficient in time but suffers from high space requirements:

The number of states in the system model grows exponentially with

- the number of variables
- the number of components in the system

# Solutions to the state-explosion problem

Symbolic model checking:

The model is represented symbolically

- BDD-based model checking
- SAT-based Bounded Model Checking (BMC)
- SAT-based Unbounded Model Checking

# Other solutions to the state-explosion problem

Small models replace the full, concrete model:

- Abstraction
- Compositional verification
- Partial order reduction
- Symmetry

# Symbolic (BDD-based) Model Checking for CTL

# BDD-based Symbolic Model Checking

A solution to the state explosion problem:  
BDD-based model checking

- **Binary Decision Diagrams ( BDDs )** are used to represent the **model** and **sets of states**.
- It can handle systems with **hundreds** of Boolean variables.

# Binary Decision Diagrams (BDDs)

- Data structure for representing Boolean functions

- **Boolean function:**

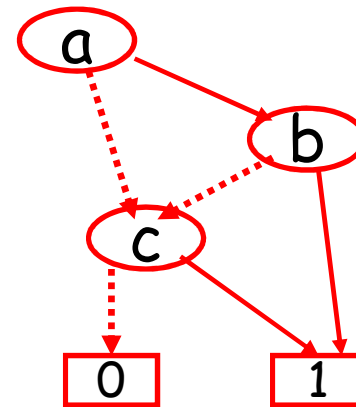
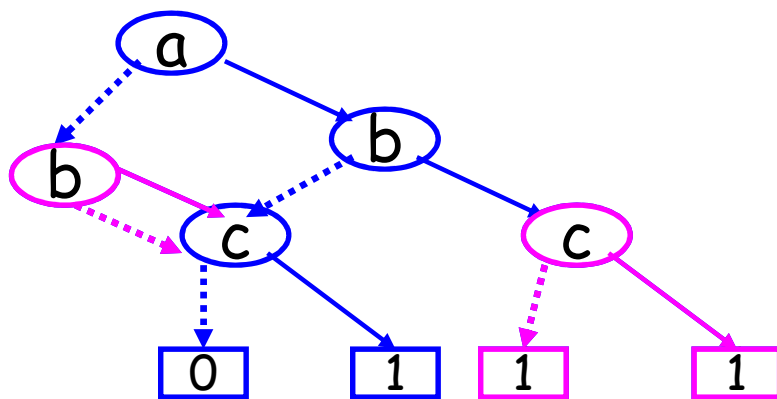
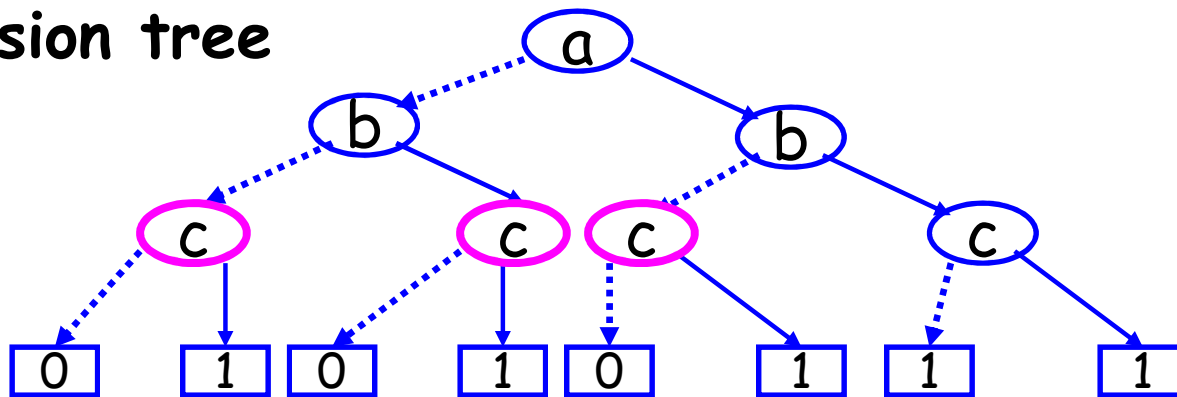
$$f: \{0,1\}^k \rightarrow \{0,1\}$$

$$f(x_1, \dots, x_k) = x_{k+1}$$

$$\text{where } x_1, \dots, x_k, x_{k+1} \in \{0,1\}$$

# BDD for $f(a,b,c) = (a \wedge b) \vee c$

Decision tree



**BDD**



# Binary Decision Diagrams (BDDs)

## Advantages of BDDs:

- Often (but not always) **concise** in size
- **Canonical** representation
- Most **Boolean operations** can be performed on BDDs in **polynomial time** in the **BDD size**

## BDDs in Model Checking

- Every set  $A \subseteq U$  can be represented by its **characteristic function**

$$f_A(u) = \begin{cases} 1 & \text{if } u \in A \\ 0 & \text{if } u \notin A \end{cases}$$

- If the elements of  $U$  are encoded by sequences over  $\{0,1\}^n$  then  $f_A$  is a **Boolean function** and can be represented by a BDD

- A Boolean function **represents** the set of all elements for which the function is **1**

## Representing a Model with BDDs

- Assume that **states** in model  $M$  are **encoded by  $\{0,1\}^n$**  and described by Boolean variables  $v_1 \dots v_n$
- $S_f$  can be represented by a Boolean function (BDD) over  $v_1 \dots v_n$
- $R$  (a set of pairs of states  **$(s, s')$** ) can be represented by a BDD over  $v_1 \dots v_n \ v'_1 \dots v'_n$

## Example: Representing a Model with BDDs

$$S = \{ s_1, s_2, s_3 \}$$

$$R = \{ (s_1, s_2), (s_2, s_2), (s_3, s_1) \}$$

**State encoding:**

$$s_1: v_1v_2=00 \quad s_2: v_1v_2=01 \quad s_3: v_1v_2=11$$

For  $A = \{s_1, s_2\}$  the Boolean formula representing A:

$$f_A(v_1, v_2) = (\neg v_1 \wedge \neg v_2) \vee (\neg v_1 \wedge v_2) = \neg v_1$$

$$R = \{ (s_1, s_2), (s_2, s_2), (s_3, s_1) \}$$

$$s_1: v_1v_2=00 \quad s_2: v_1v_2=01 \quad s_3: v_1v_2=11$$

$$\begin{aligned} f_R(v_1, v_2, v'_1, v'_2) = & \\ & (\neg v_1 \wedge \neg v_2 \wedge \neg v'_1 \wedge v'_2) \vee \\ & (\neg v_1 \wedge v_2 \wedge \neg v'_1 \wedge v'_2) \vee \\ & (v_1 \wedge v_2 \wedge \neg v'_1 \wedge \neg v'_2) \end{aligned}$$

$f_A$  and  $f_R$  can be represented by **BDDs**.