

Introduction to Software Verification

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Lectures Material
winter 2017-18

Lecture 1

Why (formal) Verification?

- Safety-critical applications:
 - Air-traffic controllers
 - Medical equipment
 - Cars

Bugs are unacceptable!

- Bugs found in later stages of design are expensive, e.g. Intel's Pentium bug in floating-point division
- Testing does not provide full coverage

The goal of the course: Formal Verification

Given

- A (model of) hardware or software system
and
- a formal specification

does the system satisfy the specification?

Not decidable!

Formal Verification

Solutions:

- “Program correctness”:
Provide **non-automated** verification methods
- “Automatic verification / Model Checking”:
restrict the problem to a decidable one:
 - **Finite-state** reactive systems
 - **Propositional** temporal logics

Specifications

- Should be given for a system by the designer, developer, programmer, user
- **Examples:**
 - Does the program always **terminate**?
 - Does the program compute correctly **multiplication** of its inputs?

Specifications

- **Additional examples:**
 - When we press a **sequence of buttons** on the control panel of an airplane / microwave - do we get **the desired result**?
 - When we **deposit money** - does it get to **our account**?
 - Can a user **access data** only if he has the appropriate **authorization**?

Verification tools

Are developed and used in

- **Hardware industry:** Intel, IBM, Cadence, Mellanox, ...
- **Software industry:** Microsoft, NASA, Amazon, Facebook...
- **Universities**

Part 1 of the course

Program Correctness

- Non-automated
- Verifies program with possibly infinite number of states
- Refers to the programs as input-output transformation

Ingredients for Formal Verification

1. Specification language

- With formal semantics

2. Programming language

- with formal semantics

3. Proof rules

- For proving "Program P has the property φ "

Requirements from the proof rules

- **Soundness of the rules:** if we were able to prove correctness of program P w.r.t. specification φ using the proof rules, then P is correct w.r.t. φ
- **Completeness of the rules:** if P is correct w.r.t. specification φ , then our proof rules can prove it

We handle:

- **Deterministic programs**
 - Exactly one computation for every input
 - At most one output for each input
- **Properties**
 - Partial correctness
 - Termination
 - Total Correctness

Some notations

- Program variables: $\bar{x} = (x_1, \dots, x_n)$
- A **state of the program** σ is a function from program variables to their domains
- The set of program states is defined by:
 $D_1 \times \dots \times D_n \cup \{\perp\}$
Where D_i is the domain of variable x_i

Program states: Examples

- A program with integer variable x , Boolean variable b
 - States: $(5, F), (-17, T)$
- Elevator on 3 floors:
 - $\text{elev_at} \in \{1, 2, 3\}$
 - $\text{on_floor1}, \text{on_floor2}, \text{on_floor3}$: Boolean
 - $\text{in_elev1}, \text{in_elev2}, \text{in_elev3}$: Boolean
 - $\text{direction} \in \{\text{up}, \text{down}\}, \text{door} \in \{\text{open}, \text{close}\}$
 - State: $(2, F, T, T, T, T, F, \text{up}, \text{close})$

Defining the Specification

Specification is a pair $\langle q_1(\bar{x}), q_2(\bar{x}) \rangle$
where:

- $q_1(\bar{x}), q_2(\bar{x})$ are first order formulas over program variables
- $q_1(\bar{x})$ describes a condition holding **before** the execution of the program
- $q_2(\bar{x})$ describes a condition holding **at the end** of the execution of the program

Examples

Specification example

- $\langle (x \geq 0 \wedge y > 0), (z = x/y \wedge z \geq 0) \rangle$

A program with $x \in \mathbb{N}, y \in \mathbb{R}, b \in \{T, F\}$

States: $(5, 5.0, T), (7, 3.111, F)$

$$q_1(x, y, b) = x > 0 \wedge b$$

$$q_2(x, y, b) = x + y > 0 \wedge \neg b$$

Computations of Programs

- $\pi(P, \sigma)$ denotes a computation of program P from state σ
- $\pi(P, \sigma)$ is a **finite** $(\sigma_1, \dots, \sigma_k)$ or **infinite** $(\sigma_1, \sigma_2, \dots)$ sequence of states where:
 - $\sigma_1 = \sigma$
 - σ_{i+1} is a result of applying an action from the program on σ_i
- This definition is *not* a full definition

More notations

- \perp - bottom : the undefined value
- $\text{val}(\pi)$ denotes the final state of computation π (if exists)
 - $\text{val}(\pi) = \sigma_k$ if $\pi = (\sigma_1, \dots, \sigma_k)$
 - $\text{val}(\pi) = \perp$ if $\pi = (\sigma_1, \sigma_2, \dots)$
 - π is an infinite computation
- $\sigma \models q(\bar{x})$ if $q(\bar{x})$ is true when free variables in q are replaced with matching values in σ

- Important remark:
 $\perp \not\models q(\bar{x})$ for every $q(\bar{x})$ (even $\perp \models \text{true}$)
- Example of formulas and their meaning:
 $q(y) = \forall x(y|x \vee 2 \nmid x)$ where x, y are naturals
 - For a state $\sigma(x)=1, \sigma(y)=2, \sigma(z)=1$
 $\sigma \models q(y)$ since $\forall x(2|x \vee 2 \nmid x)$ is true

Partial Correctness

- A program P is **partially correct** with respect to specification $\langle q_1(\bar{x}), q_2(\bar{x}) \rangle$ iff for every computation π of P from an initial point of P , and for every state σ_0 :
if
 - the computation starts from state σ_0 which **satisfies** $q_1(\bar{x})$ and
 - the computation **terminates**then
 - $q_2(\bar{x})$ holds at the end of the computation

Partial Correctness

- For every computation π and every state σ_0 :

$$(\sigma_0 \models q_1(\bar{x}) \text{ and } \text{val}(\pi(P, \sigma_0)) \neq \perp) \Rightarrow \\ \text{val}(\pi(P, \sigma_0)) \models q_2(\bar{x})$$

- Notation: $\{q_1\}P\{q_2\}$

Total Correctness

- A program P is **totally correct** with respect to specification $\langle q_1(\bar{x}), q_2(\bar{x}) \rangle$ iff for every computation π of P from an initial point of P , and for every state σ_0 :
if
 - the computation starts from state σ_0 which **satisfies** $q_1(\bar{x})$then
 - the computation **terminates**, and
 - $q_2(\bar{x})$ holds at the end of the computation

Total Correctness

- For every computation π and every state σ_0 :

$$\sigma_0 \models q_1(\bar{x}) \Rightarrow \text{val}(\pi(P, \sigma_0)) \neq \perp \text{ and} \\ \text{val}(\pi(P, \sigma_0)) \models q_2(\bar{x})$$

- Notation: $\langle q_1 \rangle P \langle q_2 \rangle$

How do we write the specification:

"P terminates if the initial state satisfies q_1 "

Separation Lemma

- For every program P and specification $\langle q_1, q_2 \rangle$:

$$\models \langle q_1 \rangle P \langle q_2 \rangle$$

if and only if

$$\models \{q_1\} P \{q_2\} \text{ and } \models \langle q_1 \rangle P \langle \text{true} \rangle$$

Examples

- Which programs satisfy $\{true\}P\{false\}$?
- Which programs satisfy $\langle true \rangle P \langle false \rangle$?

Logical Variables in Specifications

Example 1:

Specify a program with a single variable x whose value at the end of the computation is twice its value at the beginning

Logical Variables in Specifications

Solution: add **fresh variables** which are

- not part of the program and therefore
- their value does not change during the execution of the program

These variables are called **logical variables**

Convention: We use logical variable X to preserve the value of variable x

Logical Variables in Specifications

Example 2:

Program which returns in variable z the multiplication of variables x and y

Convention:

Assertions q_1, q_2 are now defined over \bar{x} that includes program variables as well as logical variables