FORMAL METHODS: PAST, PRESENT, OR FUTURE?

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software verification: a moving target





3M

5K

the past (~1979) verifying concurrency

SLIDING WINDO 4.2 OF REPORTS 159 #define MaxSeg 5 /* window size */ #define Wrong(x) HostReady the x = (x+1) percent (MaxSeq) #define Right(x) begin 1000 x = (x+1) percent (MaxSeq + 1) #define inc(x) FromHost (buffer NextFrameTo Right (x) nbuffered := nbuffered + 1; chan q[2] = [MaxSeq] of { byte, byte }; /* message passing channel */ 6 SendData (NextFrameToSend): 7 1987 active [2] proctype p5() inc (NextFrameToSend) lexi 8 { byte NextFrame, AckExp, FrameE 9 /* starte + end; 10 chan in, out; (Spin Version 6.4.4 -- 9 July 2015) FrameArrival: 14 911 in = q[_pid]; begin 12 out = q[1- pid]; + Partial Order Reduction getf(r); fe 13 xr in; xs out; /* parti; 14 if r.seg = FrameExpected the 15 do begin ff116 :: nbuf < MaxSeg -> Full statespace search for: ToHost(r.info); 017 /* outgoi nbuf++; never claim (none specified) inc (FrameExpected) 18 out !NextFrame. (FrameExp end: 19 inc(NextFrame) assertion violations lack n implies n = 1, n = 2|21:: q[_pid]?r,s -> (disabled by -DSAFETY) cycle checks while between (AckExpected, 22) /* incor if hegin 123 invalid end states :: r == FrameExp -> nbuffered := nbuffered -24 printf("MSC: accept pe StopTimer (AckExpected 25 inc(FrameExp) 26 :: else /* ignore message inc(AckExpected) 127 State-vector 68 byte, depth reached 813773, errors: 0 fi; end 28 do 6048432 states, stored 29 end :: ((AckExp <= s) && (s < No 30 3526446 states, matched ((AckExp <= s) && (NextFi 31 ((s < NextFrame) && (Next CksumErr: : 9574878 transitions (= stored+matched) 32 nbuf--; 6 million reachable states 33 Stats on memory usage (in time to verify: < 5 seconds inc (AckExp) TimeOut: 34 :: else -> break hegin 35 od NextFrameToSend := Ack#36 for i := 1 to nbuffered do 37 :: timeout -> && /* retransmis begin 38 NextFrame = AckExp; SendData (NextFrame 39 printf("MSC: timeout\n"); inc (NextFrameToSend 40 1 = 1;41 end do 42 :: i <= nbuf -> end 43 out!NextFrame, (FrameE end: 44 unreached in proctype p5 inc(NextFrame); if *ubuffered* < MaxSeg then 45 1++ tanen5:50, state 36, "-end-" 46 until doomsday :: else -> break 47 end; [protocol5] od (1 of 36 states) 48 od 49 Fig. 4-10. A sliding window process pan: elapsed time 4.5 seconds the present

pan: rate 1,344,096 states/second

COORDINATION PROBLEM IN MULTIPROCESSING SYS

present and future

- so, today we can verify problems from 1981 just fine...
 - but what about the continuing increase in complexity?
- issues that remain:
 - efficiency & scaling
 - algorithms, data structures, adaption to cloud computing
 - expressiveness & ease of use
 - logic, languages, user interfaces







how fundamental is all this? the parts of a logic model checker



automata theoretic verification



formal methods = computer science
 (logic +
 data structures +
 algorithms)

USE LOGIC

+ the chance to work on some really important problems



